

# *Introduction to Neural Networks*

# **Introduction**

# Introduction

- **Why ANN**

- Some tasks can be done easily (effortlessly) by humans but are hard by conventional paradigms on Von Neumann machine with algorithmic approach
  - Pattern recognition (old friends, hand-written characters)
  - Content addressable recall
  - Approximate, common sense reasoning (driving, playing piano, baseball player)
- These tasks are often ill-defined, experience based, hard to apply logic

# Introduction

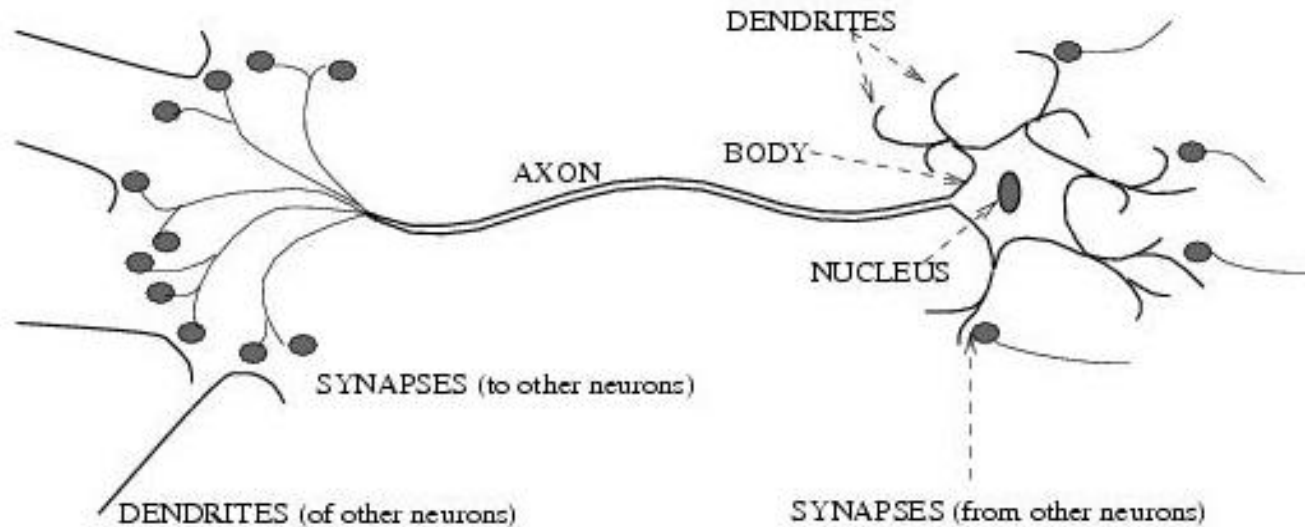
## Von Neumann machine

- One or a few high speed (ns) processors with considerable computing power
- One or a few shared high speed buses for communication
- Sequential memory access by address
- Problem-solving knowledge is separated from the computing component
- Hard to be adaptive

## Human Brain

- Large # ( $10^{11}$ ) of low speed processors (ms) with limited computing power
- Large # ( $10^{15}$ ) of low speed connections
- Content addressable recall (CAM)
- Problem-solving knowledge resides in the connectivity of neurons
- Adaptation by changing the connectivity

## • Biological neural activity



- Each neuron has a *body*, an *axon*, and many *dendrites*
  - Can be in one of the two states: *firing* and *rest*.
  - Neuron fires if the total incoming stimulus exceeds the threshold
- *Synapse*: thin gap between axon of one neuron and dendrite of another.
  - Signal exchange
  - Synaptic strength/efficiency

# Introduction

- **What is an (artificial) neural network**
  - A set of **nodes** (units, neurons, processing elements)
    - Each node has input and output
    - Each node performs a simple computation by its **node function**
  - **Weighted connections** between nodes
    - Connectivity gives the structure/architecture of the net
    - What can be computed by a NN is primarily determined by the connections and their weights
  - A very much simplified version of networks of neurons in animal nerve systems

# Introduction

## ANN

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- **Nodes**
  - input
  - output
  - node function
- **Connections**
  - connection strength

## Bio NN

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- **Cell body**
  - signal from other neurons
  - firing frequency
  - firing mechanism
- **Synapses**
  - synaptic strength

- Highly parallel, simple local computation (at neuron level) achieves global results as emerging property of the interaction (at network level)
- Pattern directed (meaning of individual nodes only in the context of a pattern)
- Fault-tolerant/graceful degrading
- Learning/adaptation plays important role.

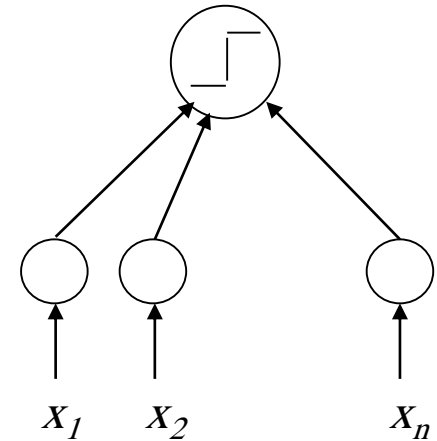
# History of NN

- **Pitts & McCulloch (1943)**
  - First mathematical model of biological neurons
  - All Boolean operations can be implemented by these neuron-like nodes (with different threshold and excitatory/inhibitory connections).
  - Competitor to Von Neumann model for general purpose computing device
  - Origin of automata theory.
- **Hebb (1949)**
  - Hebbian rule of learning: increase the connection strength between neurons  $i$  and  $j$  whenever both  $i$  and  $j$  are activated.
  - Or increase the connection strength between nodes  $i$  and  $j$  whenever both nodes are simultaneously ON or OFF.



# History of NN

- **Early booming (50's – early 60's)**
  - Rosenblatt (1958)
    - Perceptron: network of threshold nodes for pattern classification
    - Perceptron learning rule
    - Perceptron convergence theorem: everything that can be represented by a perceptron can be learned
  - Widrow and Hoff (1960, 1962)
    - Learning rule based on gradient descent (with differentiable unit)
  - Minsky's attempt to build a general purpose machine with Pitts/McCulloch units



# History of NN

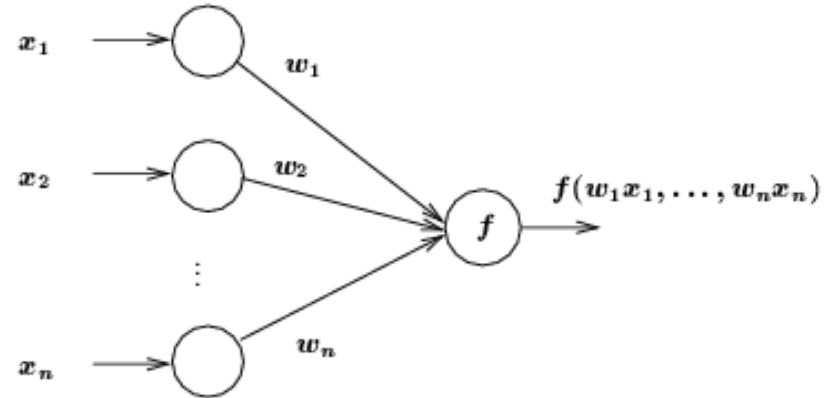
- **The setback (mid 60's – late 70's)**
  - Serious problems with perceptron model (Minsky's book 1969)
    - Single layer perceptrons cannot represent (learn) simple functions such as XOR
    - Multi-layer of non-linear units may have greater power but there is no learning rule for such nets
    - Scaling problem: connection weights may grow infinitely
  - The first two problems overcame by latter effort in 80's, but the scaling problem persists
  - Death of Rosenblatt (1964)
  - Striving of Von Neumann machine and AI

# History of NN

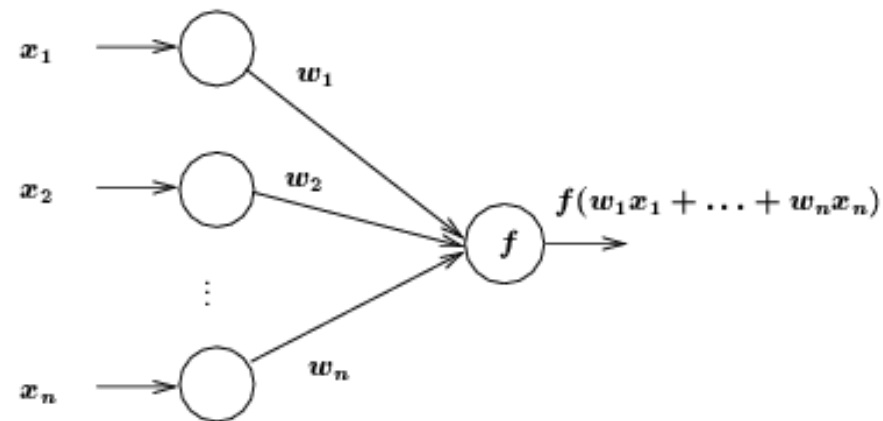
- **Renewed enthusiasm and flourish (80's – present)**
  - New techniques
    - Backpropagation learning for multi-layer feed forward nets (with non-linear, differentiable node functions)
    - Thermodynamic models (Hopfield net, Boltzmann machine, etc.)
    - Unsupervised learning
  - Impressive application (character recognition, speech recognition, text-to-speech transformation, process control, associative memory, etc.)
  - Traditional approaches face difficult challenges
  - Caution:
    - Don't underestimate difficulties and limitations
    - Poses more problems than solutions

# ANN Neuron Models

- Each node has one or more inputs from other nodes, and one output to other nodes
- Input/output values can be
  - Binary  $\{0, 1\}$
  - Bipolar  $\{-1, 1\}$
  - Continuous
- All inputs to one node come in at the same time and remain activated until the output is produced
- Weights associated with links
- $f(\text{net})$  is the node function  
 $\text{net} = \sum_{i=1}^n w_i x_i$  is most popular



General neuron model



Weighted input summation

# Node Function

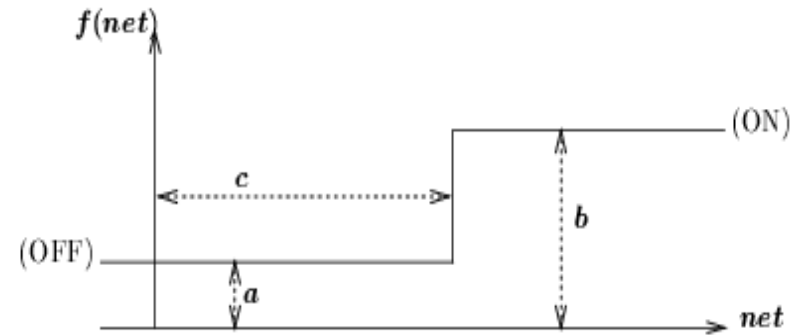
- Identity function:  $f(\text{net}) = \text{net}$ .
- Constant function:  $f(\text{net}) = c$ .
- Step (threshold) function

$$f(\text{net}) = \begin{cases} a & \text{if } \text{net} < c \\ b & \text{if } \text{net} > c \end{cases}$$

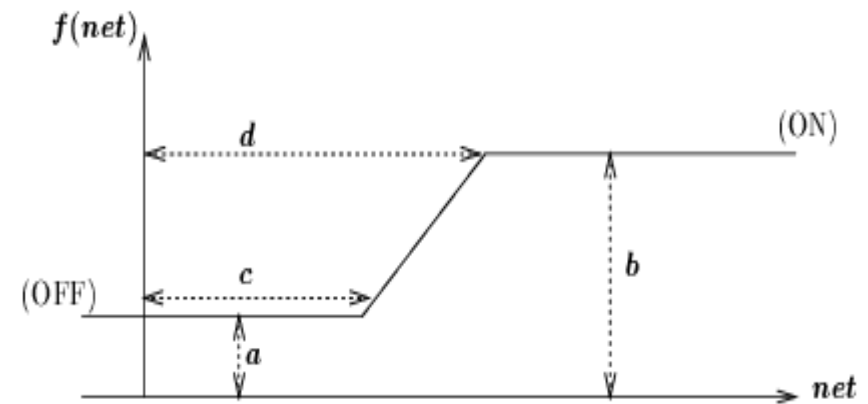
where  $c$  is called the threshold

- Ramp function

$$f(\text{net}) = \begin{cases} a & \text{if } \text{net} \leq c \\ b & \text{if } \text{net} \geq d \\ a + \frac{(\text{net}-c)(b-a)}{(d-c)} & \text{otherwise} \end{cases}$$



Step function



Ramp function

# Node Function

- **Sigmoid function**

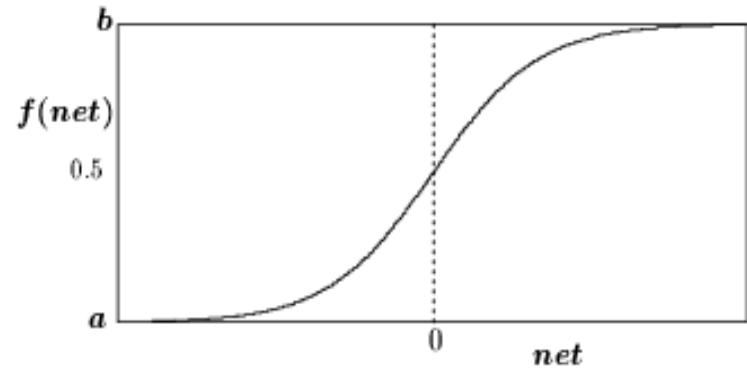
- S-shaped
- Continuous and everywhere differentiable
- Rotationally symmetric about some point ( $net = c$ )
- Asymptotically approach saturation points

$$\lim_{net \rightarrow -\infty} f(net) = a \quad \lim_{net \rightarrow \infty} f(net) = b$$

- Examples:

$$f(net) = z + \frac{1}{1 + \exp(-x \cdot net + y)}$$

$$f(net) = \tanh(x \cdot net - y) + z,$$



Sigmoid function

When  $y = 0$  and  $z = 0$ :

$$a = 0, b = 1, c = 0.$$

When  $y = 0$  and  $z = -0.5$

$$a = -0.5, b = 0.5, c = 0.$$

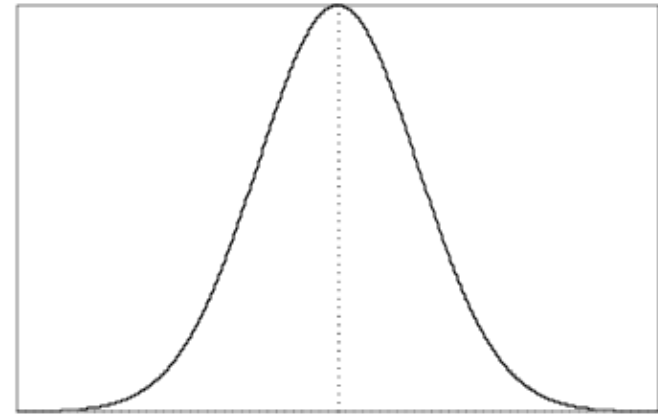
Larger  $x$  gives steeper curve

# Node Function

- **Gaussian function**

- Bell-shaped (radial basis)
- Continuous
- $f(\text{net})$  asymptotically approaches 0 (or some constant) when  $|\text{net}|$  is large
- Single maximum (when  $\text{net} = \mu$ )
- Example:

$$f(\text{net}) = \frac{1}{\sqrt{2\pi}\sigma} \exp \left[ -\frac{1}{2} \left( \frac{\text{net} - \mu}{\sigma} \right)^2 \right]$$

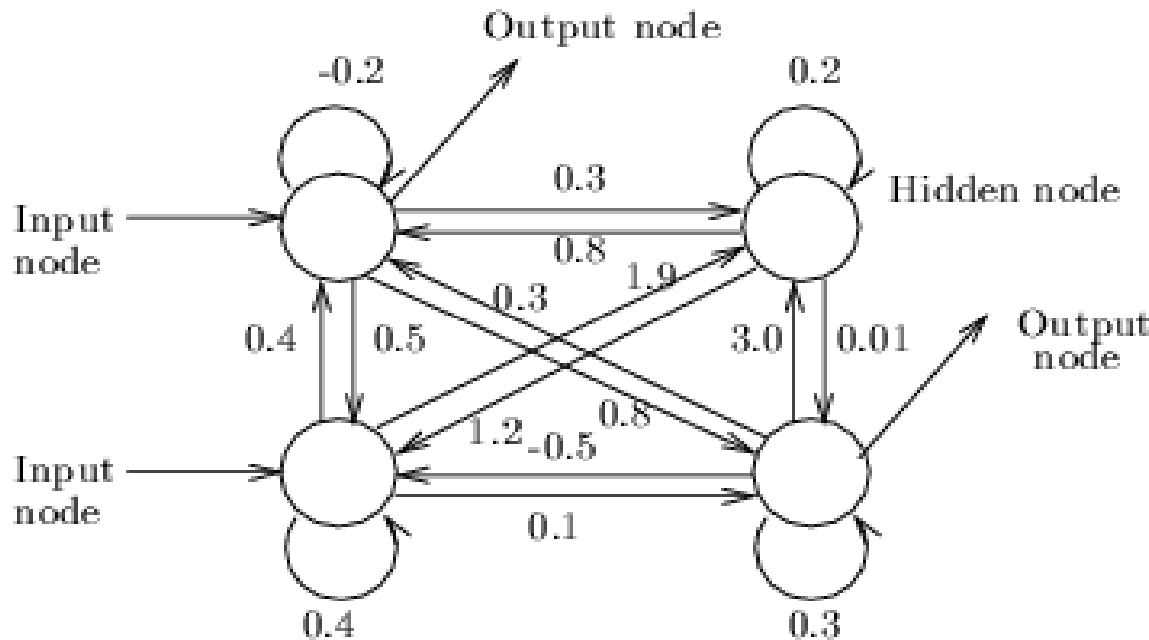


Gaussian function

# Network Architecture

- **(Asymmetric) Fully Connected Networks**

- Every node is connected to every other node
- Connection may be excitatory (positive), inhibitory (negative), or irrelevant ( $\approx 0$ ).
- Most general
- Symmetric fully connected nets: weights are symmetric ( $w_{ij} = w_{ji}$ )



**Input nodes:** receive input from the environment

**Output nodes:** send signals to the environment

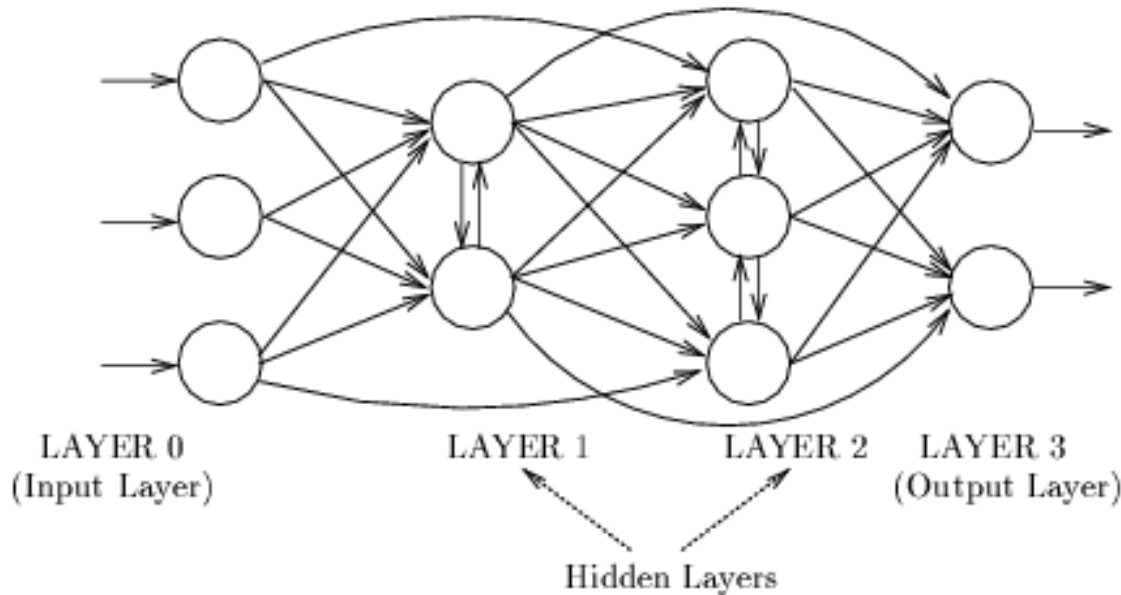
**Hidden nodes:** no direct interaction to the environment



# Network Architecture

- **Layered Networks**

- Nodes are partitioned into subsets, called layers.
- No connections that lead from nodes in layer  $j$  to those in layer  $k$  if  $j > k$ .

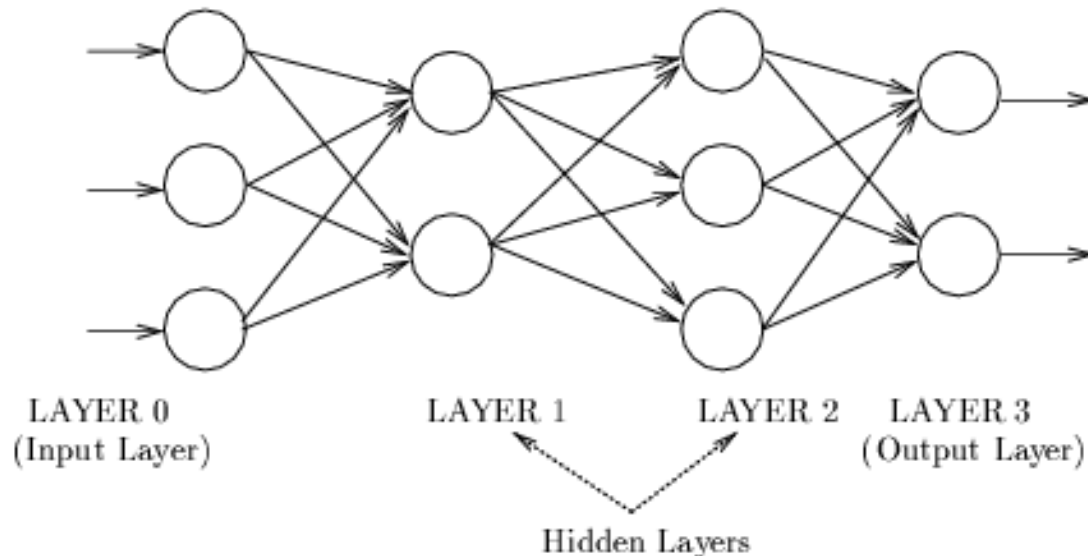


- Inputs from the environment are applied to nodes in layer 0 (**input layer**).
- Nodes in input layer are place holders with no computation occurring (i.e., their node functions are identity function)

# Network Architecture

- **Feedforward Networks**

- A connection is allowed from a node in layer  $i$  only to nodes in layer  $i + 1$ .
- Most widely used architecture.



Conceptually, nodes at higher levels successively abstract features from preceding layers

# Network Architecture

- **Acyclic Networks**
  - Connections do not form directed cycles.
  - Multi-layered feedforward nets are acyclic
- **Recurrent Networks**
  - Nets with directed cycles.
  - Much harder to analyze than acyclic nets.
- **Modular nets**
  - Consists of several modules, each of which is itself a neural net for a particular sub-problem
  - Sparse connections between modules